
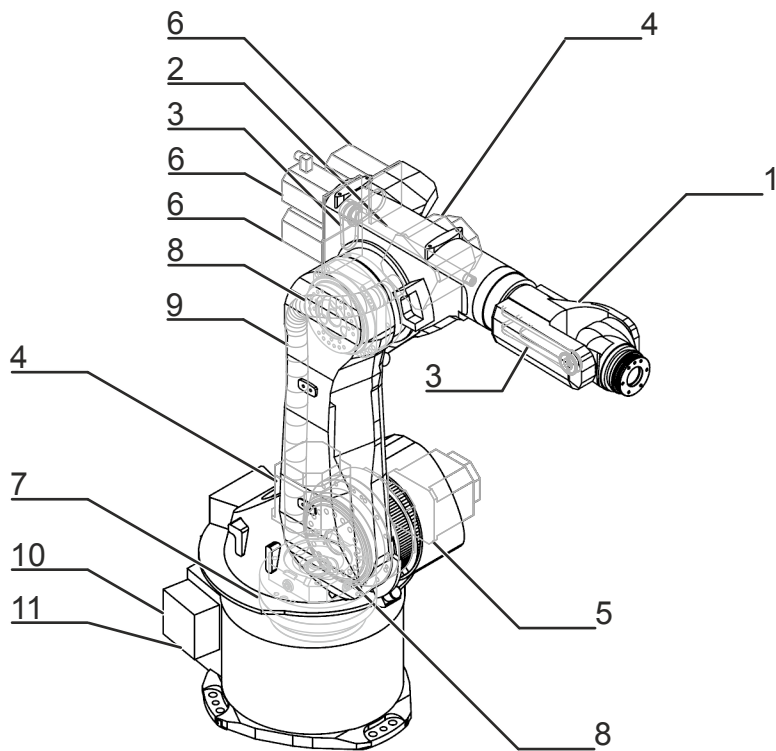


# KUKA | Xpert

Identification number: AR6207

货号	0000-179-777
材料状态	10 - 批准预生产
制造商	KUKA Roboter
产品图片	

# Spare parts



Spare parts graphic KR 30 L16-2 , schematic representation

Pos.	Article number	Designation	Component
1	0000-213-130	SPP ZH 16 II	In-line wrist
2	0000-176-708	Drive train KR 30 L 16-3 A6: N10x...	Connecting shaft
3	0000-122-486	Tooth.belt, Synchrofl.16 AT 5/525-E5/7.5	Toothed belt A4 Toothed belt A5
4	0000-192-296	SPP AC servomotor G1/1FK7100	Motor A1 Motor A3
5	0000-221-099	SPP AC servomotor TYPE K/1FK7103	Motor A2
6	0000-115-926	ME 60 110 30 S0	Motor A4 Motor A5 Motor A6
7	0071-050-782	Gear unit RV-320EL-184	Gear A1

Pos.	Article number	Designation	Component
8	0000-264-429	Preassembly of gear unit RV-320E-185	Gear A2 Gear A3
9	0000-186-722	KRC4 robot cable set assy KR30L16	Cable set
	0000-132-240	Standard cable set with RDC, KR 30L16	
	0000-139-783	Safe cable set assy, KR 30L16	
10	0000-246-872	Resolver Digital Converter RDC	RDC
11	0000-172-903	Electronic Data Storage EDS	EDS
12	0000-119-966	RDC 2 Resolver Digital Converter 120MHz	
13	0000-194-084	Safe RDC w. I/O print spare part	

Export to Excel 

# Maintenance information

## Gear oil



The quantity of oil drained depends on the draining time and the oil temperature. The refilling quantity is the quantity of oil that was drained from the gear unit at the correct operating temperature and with the correct draining time. This oil quantity must be determined. Only this quantity of oil may be used when refilling.

If less than 70 % of the specified oil quantity flows out, flush the gear unit with the determined quantity of drained oil once, then pour in the amount of oil that was drained. If less than 50% of the specified oil quantity flows out (e.g. inclined installation), the flushing operation must be repeated twice. During the flushing procedure, move the axis at jog velocity throughout the entire axis range.

The oil quantities specified in the table correspond to the oil quantities in the gear unit at first filling.

Gear oil new filling quantity	
A1	3.30 l
A2	1.00 l
A3	1.00 l
A4	0.32 l
A5	0.16 l
A6	0.18 l
Gear oil refilling quantity	
A1	1.70 l
A2	0.90 l
A3	0.90 l
A4	0.31 l
A5	0.14 l
A6	0.14 l

# Toothed belt tension

Toothed belt tension motor	
A4	95 ± 2 Hz
A5	95 ± 2 Hz
A6	-
Toothed belt tension inline wrist	
A5	-
A6	-

# 技术数据

## 基本数据

	<b>KR 30 L16-2</b>
轴数	6
可控制的轴数	6
工作空间体积	104.5 m <sup>3</sup>
位姿重复精度 (ISO 9283)	± 0.07 mm
重量	约 700 kg
额定负荷	16 kg
最大负载能力	-
最大运动范围	3102 mm
防护等级 (IEC 60529)	IP64
机器人腕部防护等级 (IEC 60529)	IP65
噪声等级	< 75 dB (A)
安装位置	地面
占地面积	850 mm x 850 mm
运动系统安装面布孔图	-
允许倾角	-
标准色	底座： 黑色 (RAL 9005); 活动部件： 库卡橙色 2567
控制系统	KR C4
变压器名称	KR C4: KR30L16_3A C4 FLR ZH16_2

# 环境条件

湿度等级 (EN 60204)	-
环境条件分类 (EN 60721-3-3)	3K3
环境温度	
运行时	10 °C 至 55 °C (283 K 至 328 K)
仓储和运输时	-40 °C 至 60 °C (233 K 至 333 K)

# 轴数据

运动范围	
A1	±185 °
A2	-135 ° / 35 °
A3	-120 ° / 158 °
A4	±350 °
A5	±130 °
A6	±350 °
额定负载时的速度	
A1	100 °/s
A2	80 °/s
A3	80 °/s
A4	230 °/s
A5	165 °/s
A6	249 °/s

# 负载能力

额定负荷	16 kg
最大负载能力	-
法兰 <b>I<sub>x</sub></b> 额定质量转动惯量	0.36 kgm <sup>2</sup>
法兰 <b>I<sub>y</sub></b> 额定质量转动惯量	0.36 kgm <sup>2</sup>
法兰 <b>I<sub>z</sub></b> 额定质量转动惯量	0.36 kgm <sup>2</sup>
底座的额定附加负载	0 kg
底座的最大附加负载	-
转盘的额定附加负载	0 kg
旋转机构的最大附加负载	0 kg
大臂的额定附加负载	0 kg
大臂的最大附加负载	0 kg
小臂的额定附加负载	35 kg
小臂的最大附加负载	35 kg
负载重心额定距离	
<b>L<sub>xy</sub></b>	120 mm
<b>L<sub>z</sub></b>	150 mm



# 地基负载

纵向动力 <b>F(v)</b>	
<b>F(v 正常)</b>	9000 N
<b>F(vmax)</b>	13600 N
横向动力 <b>F(h)</b>	
<b>F(h 正常)</b>	6950 N
<b>F(hmax)</b>	12300 N
倾覆力矩 <b>M(k)</b>	
<b>M(k 正常)</b>	11900 Nm
<b>M(kmax)</b>	21600 Nm
轴 2 转矩 <b>M(r)</b>	
<b>M(r 正常)</b>	6850 Nm
<b>M(rmax)</b>	18400 Nm

垂直力  $F(v)$ 、水平力  $F(h)$ 、倾斜力矩  $M(k)$ 、轴 1 的转矩  $M(r)$

# Process forces

Process forces are forces that are exerted on the robot in a defined manner by an external influence. Causes include pressing processes and machining tasks carried out by the robot. The process forces that the robot can withstand depend to a very great degree on the robot position, payload, direction and duration of action. For this reason, it is not possible for a simple limit value to be specified for permissible process forces.

Permissible process torques are therefore specified for all axes of the robot. These values indicate the torque that each robot axis can withstand on a sustained basis as a result of external forces.

The following load torques must not be exceeded:

<b>A1</b>	-
<b>A2</b>	-
<b>A3</b>	-
<b>A4</b>	51.9 Nm
<b>A5</b>	51.9 Nm
<b>A6</b>	18.8 Nm

# Flange loads

## Flange loads

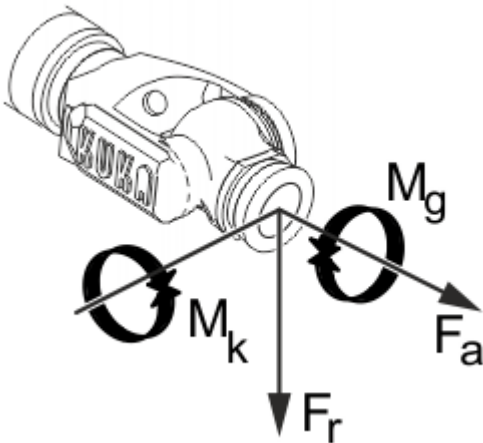
Due to the motion of the payload (e.g. tool) mounted on the robot, forces and torques act on the mounting flange. These forces and torques depend on the motion profile as well as the mass, load center of gravity and mass moment of inertia of the payload.

The specified values refer to nominal payloads at the nominal distance and do not include safety factors. It is imperative for the load data to be entered in the robot controller. The robot controller takes the payload into consideration during path planning. A reduced payload does not necessarily result in lower forces and torques.

The values are guide values determined by means of trial and simulation and refer to the most heavily loaded machine in the robot family. The actual forces and torques may differ due to internal and external influences on the mounting flange or a different point of application. It is therefore advisable to determine the exact forces and torques where necessary on site under the real conditions of the actual robot application.

The operating values may occur permanently in the normal motion profile. It is advisable to rate the tool for its fatigue strength.

The EMERGENCY STOP values may arise in the event of an Emergency Stop situation of the robot. As these should only occur very rarely during the service life of the robot, a static strength verification is usually sufficient.



Flange loads

Flange loads during operation	
<b>F(a)</b>	810 N
<b>F(r)</b>	741 N
<b>M(k)</b>	76 Nm

<b>M(g)</b>	61 Nm
<b>Flange loads in the case of EMERGENCY STOP</b>	
<b>F(a)</b>	859 N
<b>F(r)</b>	1306 N
<b>M(k)</b>	157 Nm
<b>M(g)</b>	117 Nm

Axial force  $F(a)$ , radial force  $F(r)$ , tilting torque  $M(k)$ , torque about mounting flange  $M(g)$

# 关税信息

统计货号	84795000
原产地	DE
制造商	KUKA ROBOTER
重量	700 kg

- 
- > **KR 30 L16-2** 带有如下的工具 (6)
  - > **KR 30 L16-2** 有以下选项 (38)
  - > **KR 30 L16-2** 带有如下的标准组件 (4)
  - > **KR 30 L16-2** 需要 (22)
  - > **KR 30 L16-2** 带有如下的备件 (14)